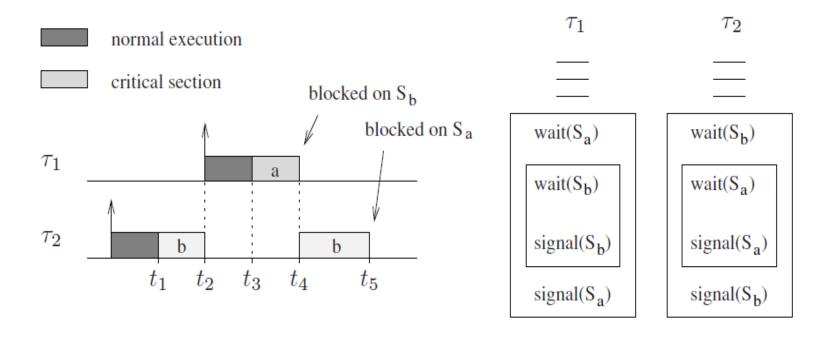
# Real Time Systems 1 lecture 10

**Priority Ceiling Protocol** 



**Figure 7.13** Example of deadlock.

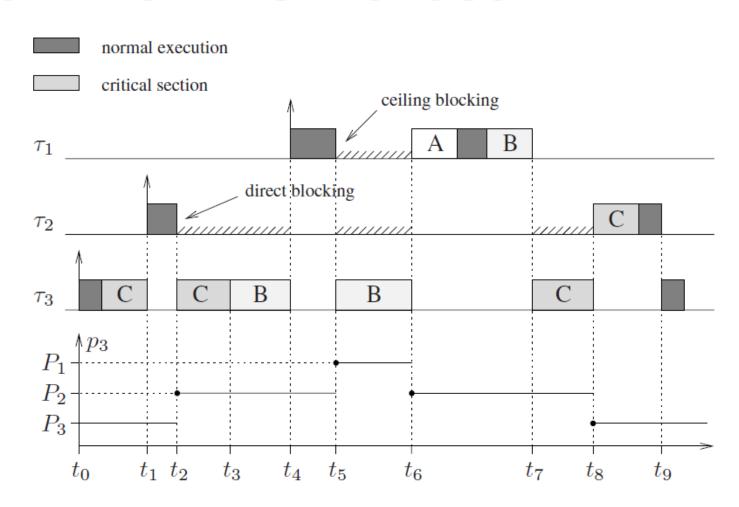
The Priority Ceiling Protocol (PCP) was introduced by Sha, Rajkumar, and Lehoczky [SRL90] to bound the priority inversion phenomenon and prevent the formation of deadlocks and chained blocking.

- The basic idea of this method is to extend the Priority Inheritance Protocol with a rule for granting a lock request on a free semaphore.
- To avoid multiple blocking, this rule does not allow a task to enter a critical section if there are locked semaphores that could block it.
- This means that once a task enters its first critical section, it can never be blocked by lower-priority tasks until its completion

- In order to realize this idea, each semaphore is assigned a *priority ceiling* equal to the highest priority of the tasks that can lock it.
- Then, a task  $\tau$  *i* is allowed to enter a critical section only if its priority is higher than all priority ceilings of the semaphores currently locked by tasks other than  $\tau i$ .

- The Priority Ceiling Protocol can be defined as follows:
- ▶ 1. Each semaphore Sk is assigned a priority ceiling C(Sk) equal to the highest priority of the tasks that can lock it. Note that C(Sk) is a static value that can be computed off-line: C(Sk) def = max I(Pi)  $Sk \in \sigma i$ .
- 2. Let  $\tau i$  be the task with the highest priority among all tasks ready to run; thus,  $\tau$  / is assigned the processor.

- ▶ 3. Let S\* be the semaphore with the highest ceiling among all the semaphores currently locked by tasks other than  $\tau i$  and let C(S\*) be its ceiling.
- 4. To enter a critical section guarded by a semaphore Sk,  $\tau i$  must have a priority higher than C(S\*).
- If  $Pi \leq C(S*)$ , the lock on Sk is denied and  $\tau i$  is said to be blocked on semaphore S\* by the task that holds the lock on S\*.



**Figure 7.14** Example of Priority Ceiling Protocol.

Figure 8-10 shows the schedule of the system of jobs when their accesses to resources are controlled by the priority-ceiling.

Job	$r_i$	$e_i$	$\pi_i$	Critical Sections
$J_1$	7	3	1	[Shaded; 1]
$J_2$	5	3	2	[Black; 1]
$J_1$	4	2	3	
$J_4$	2	6	4	[Shaded; 4 [Black; 1.5]]
$J_5$	0	6	5	[Black; 4]

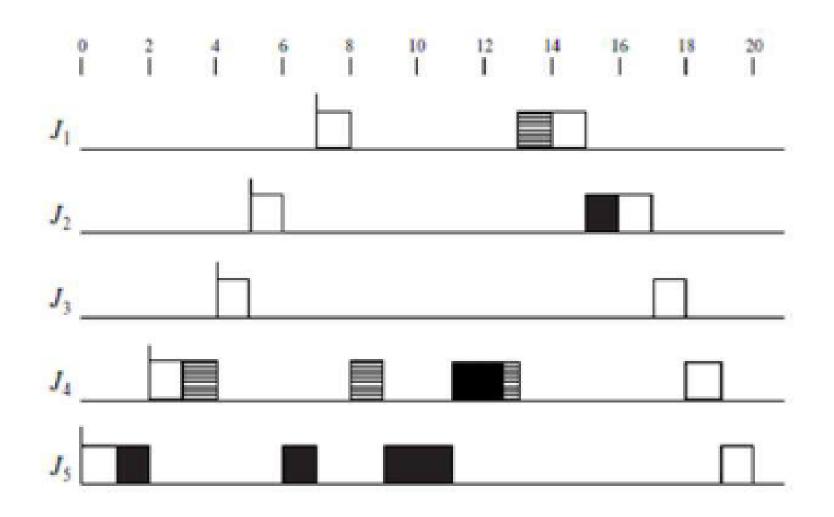


Figure 8-8 Example of Priority priority-inheritance Protocol

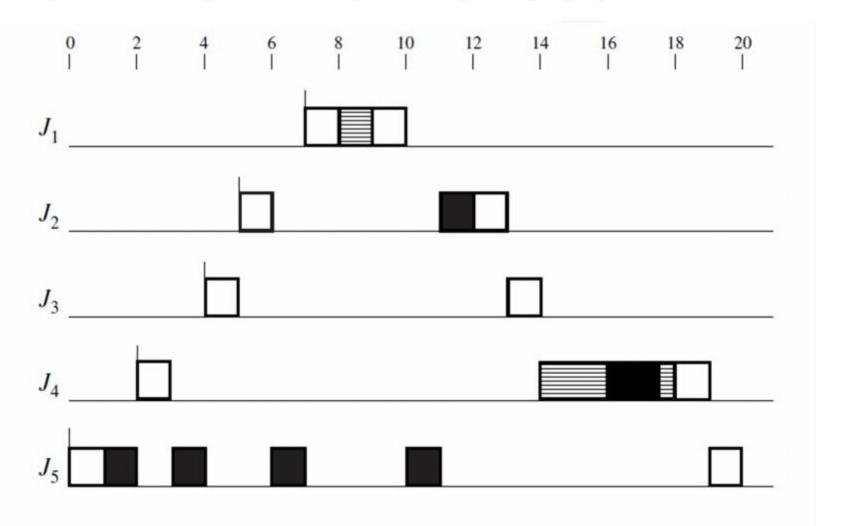


Figure 8-10 Example of Priority Ceiling Protocol

- As stated earlier, the priority ceilings of the resources *Black* and *Shaded* are 2 and 1, respectively.
- 1. In the interval (0, 3], this schedule is the same as the schedule shown in Figure 8-8, which is produced under the basic priority-inheritance protocol.
- In particular, the ceiling of the system at time 1 is . When J5 requests Black, it is allocated the resource.

After *Black* is allocated, the ceiling of the system is raised to 2, the priority ceiling of *Black*.

2. At time 3, J4 requests Shaded. Shaded is free; however, because the ceiling (= 2) of the system and its higher than the priority of J4, J4's request is denied. J4 is blocked, and J5 inherits J4's priority and executes at priority 4.

- ▶ 3. At time 4, /3 preempts /5, and at time 5, /2 preempts /3. At time 6, /2 requests *Black* and becomes directly blocked by /5.
- Consequently, J5 inherits the priority 2; it executes until J1 becomes ready and preempts it.
- During all this time, the ceiling of the system remains at 2.
- 4. When /1 requests Shaded at time 8, its priority is higher than the ceiling of the system.
- Hence, its request is granted, allowing it to enter its critical section and complete by the time 10.

- At time 10, \( \int \) and \( \int \) are ready. The latter has a higher priority (i.e., 2); it resumes
- 5. At 11, when J5 releases Black, its priority returns to 5, and the ceiling of the system drops to 5. J2 becomes unblocked, is allocated Black, and starts to execute.
- 6. At time 14, after J2 and J3 complete, J4 has the processor and is granted the resource Shaded because its priority is higher than the ceiling of the system at that time. It starts to execute.

- The ceiling of the system is raised to 1, the priority ceiling of Shaded.
- 7. At time 16, J4 requests Black, which is free. The priority of J4 is lower than 1, but J4 is the job holding the resource (i.e., Shaded) whose priority ceiling is equal to 1.
- Hence, J4 is granted Black. It continues to execute. The rest of the schedule is selfexplanatory.

- Comparing the schedules in figures 8-8 and 8-10, we see that when priority-ceiling protocol is used, *J*4 is blocked at time 3.
- A consequence is that the higher priority jobs /1, /2, and /3 all complete earlier at the expense of the lower priority job /4.
- This is the desired effect of the protocol

HW:

task	ri	ei	recourses
T1	10	4	A:1
T2	7	4	A:1, B:1
T3	4	4	B:1, C:1
T4	0	11	[A:5 [B:2]]