

## 2D Transformations

Transformation means changing some graphics into something else by applying rules.

There are various types of transformations such as translation, scaling up or down, rotation, shearing, etc. When a transformation takes place on a 2D plane, it is called 2D transformation.

Transformations play an important role in computer graphics to reposition the graphics on the screen and change their size or orientation.

### Fundamental Transformation

There are several basic transformations:

- 1- Translation (Shift or Move).
- 2- Scaling.
- 3- Rotation.
- 4- Reflection.
- 5- Shear.

### Homogenous Coordinates

To shorten the process of sequence of transformations, we have to use  $3 \times 3$  transformation matrix instead of  $2 \times 2$  transformation matrix. To convert a  $2 \times 2$  matrix to  $3 \times 3$  matrix, we have to add an extra dummy coordinate  $W$ .

In this way, we can represent the point by 3 numbers instead of 2 numbers, which is called **Homogenous Coordinates** system. In this system, we can represent all the transformation equations in matrix multiplication. Any Cartesian point  $P(X, Y)$  can be converted to homogenous coordinates by  $P^h (X_h, Y_h, h)$ .

#### 1- Translation

Consider a point  $p(x, y)$ . we can translate it means shift it to new position  $p^h(x', y')$  by adding  $t_x$  and  $t_y$  in  $x$  and  $y$  where  $T_x$  and  $T_y$  are translating factor. Mathematically this can be represented as:

$$\begin{aligned}x' &= x + T_x \\ y' &= y + T_y\end{aligned}$$

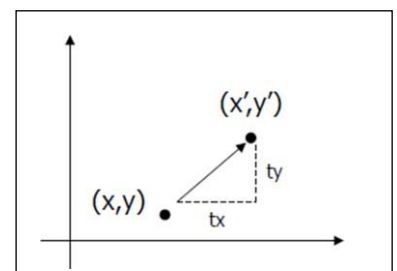
Note that: Using coordinate system the translating factors are: If

$T_x > 0$  then point moves to the right.

If  $T_x < 0$  then point moves to the left. If

$T_y > 0$  then point moves to the up.

If  $T_y < 0$  then point moves to the down.



Matrix representation: Each of two dimensional transformations can be presented as a product of the row vector  $(x\ y\ 1)$  and an  $3 \times 3$  matrix.

$$(x' y' 1) = (x\ y\ 1) * \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ tx & ty & 1 \end{bmatrix}$$

$$[x', y', 1] = [x + tx, y + ty, 1]$$

**Ex.1:** Translate the following points: (5,10), (50,10), (30,20), as:

1- 10 points right, 5 points up,

2- 5 points left, 7 points down,

3- 2 points right, 0 points down,

**Sol.:**

1-  $tx=10, ty=5$ ,

(5+10, 10+5), (50+10, 10+5), (30+10, 20+5)  
(15,15) (60,15) (40,25)

2-  $tx=-5, ty=-7$

(0,3) (45,3) (25,13)

3-  $tx=2, ty=0$

(7,10) (52,10) (32,20)

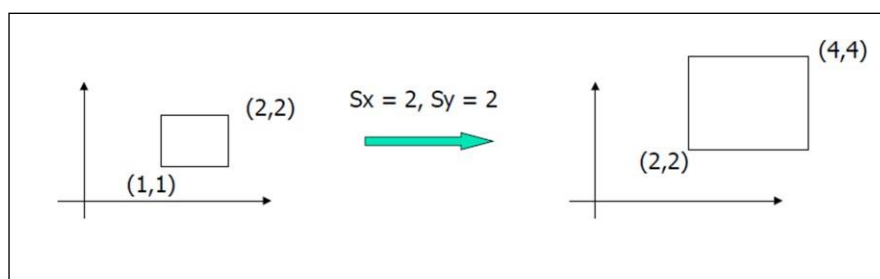
## 2- Scaling

To change the size of an object such that we can magnify the size or reduce it. This process is called scaling. Suppose  $p(x,y)$  is the point which we want to scale, after scaling we get new point having coordinates as  $p'(x',y') \Rightarrow x' = x * S_x, y' = y * S_y$  where  $S_x$  and  $S_y$  are scaling factors.

Whenever scaling is performed there is one point that remains of the same location called the fixed point of scaling. If the fixed point is at the origin (0,0) a point  $(x, y)$  can be scaled by a factor  $S_x$  in the x direction and by  $S_y$  in the y direction.

$$x' = x * S_x$$

$$y' = y * S_y$$



Matrix representation:

$$\begin{aligned} (x'y'1) &= (x\ y\ 1) * \begin{bmatrix} Sx & 0 & 0 \\ 0 & Sy & 0 \\ 0 & 0 & 1 \end{bmatrix} \\ [x',\ y',\ 1] &= [x*Sx,\ y*Sy,\ 1] \end{aligned}$$

**Ex.2:** Scale the following points (5,5), (10,5), (5,10), (10,10), for  $Sx=Sy=1$ , (uniform scaling).

**Sol.:**  $p_1(2.5,2.5), p_2(2.5,2.5), p_3(2.5,2.5), p_4(2.5,2.5)$