# Real Time Systems 1 lecture 9

- The *Priority Inheritance Protocol* (PIP), proposed by Sha, Rajkumar and Lehoczky [SRL90], avoids unbounded priority inversion by modifying the priority of those tasks that cause blocking.
- In particular, when a task *ti* blocks one or more higher-priority tasks, it temporarily assumes (*inherits*) the highest priority of the blocked tasks.

- This prevents medium-priority tasks from preempting  $\tau$  *i* and prolonging the blocking duration experienced by the higher-priority tasks.
- The Priority Inheritance Protocol can be defined as follows:
- 1. Tasks are scheduled based on their active priorities. Tasks with the same priority are executed in a First Come First Served discipline.

- 2. When task  $\tau i$  tries to enter a critical section zi,k and resource Rk is already held by a lower-priority task  $\tau j$ , then  $\tau i$  is blocked.  $\tau i$  is said to be blocked by the task  $\tau j$  that holds the resource. Otherwise,  $\tau i$  enters the critical section zi,k.
- 3. When a task  $\tau i$  is blocked on a semaphore, it transmits its active priority to the task, say  $\tau j$ , that holds that semaphore.

- Hence,  $\tau j$  resumes and executes the rest of its critical section with a priority pj = pi. Task  $\tau j$  is said to *inherit* the priority of  $\tau i$ . In general, a task inherits the highest priority of the tasks it blocks. That is, at every instant,  $pj(Rk) = \max\{Pj , \max h \{Ph/\tau h \text{ is blocked on } Rk\}\}$ .
- 4. When *tj* exits a critical section, it unlocks the semaphore, and the highest-priority task blocked on that semaphore, if any, is awakened.

- The active priority of  $\tau j$  is updated as follows: if no other tasks are blocked by  $\tau j$ , pj is set to its nominal priority Pj; otherwise it is set to the highest priority of the tasks blocked by  $\tau j$ , according to Equation (7.8).
- 5. Priority inheritance is transitive; that is, if a task  $\tau$ 3 blocks a task  $\tau$ 2, and  $\tau$ 2 blocks a task  $\tau$ 1, then  $\tau$ 3 inherits the priority of  $\tau$ 1 via  $\tau$ 2.

# Priority Inheritance Protocol Example

- There are five jobs and two resources *Black* and *Shaded*. The parameters of the jobs and their critical sections are listed in part (a). As usual, jobs are indexed in decreasing order of their priorities:
- The priority *πi* of *Ji* is *i*, and the smaller the integer, the higher the priority. In the schedule in part (b) of this figure, black boxes show the critical sections when the jobs are holding *Black*.
- Shaded boxes show the critical sections when the jobs are holding Shaded

#### Priority Inheritance Protocol Example

Job	$r_i$	$e_i$	$\pi_i$	Critical Sections
$J_1$	7	3	1	[Shaded; 1]
$J_2$	5	3	2	[Black; 1]
$J_3$	4	2	3	
$J_4$	2	6	4	[Shaded; 4 [Black; 1.5]]
J <sub>5</sub>	0	6	5	[Black; 4]

(a)

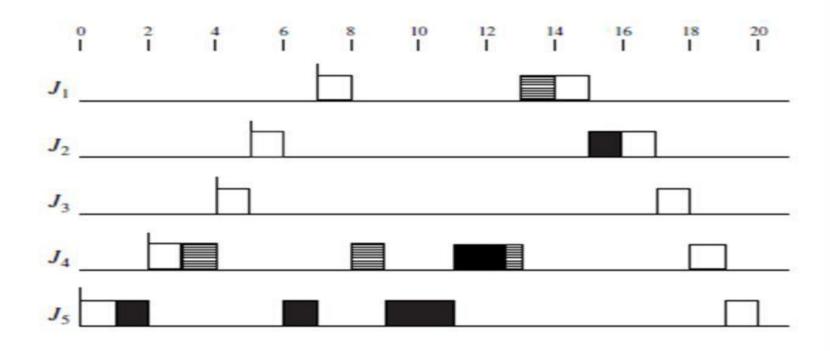


FIGURE 8-8 Example illustrating transitive inheritance of priority inheritance. (a) Parameters of jobs. (b) Schedule under priority inheritance.

(b)

- 1. At time 0, job J5 becomes ready and executes at its assigned priority 5. At time 1, it is granted the resource Black.
- 2. At time 2, J4 is released. It preempts J5 and starts to execute.
- 3. At time 3, J4 requests Shaded. Shaded, being free, is granted to the job. The job continues to execute.
- 4. At time 4, \( \int \) is released and preempts \( \int \)4. At time 5, \( \int \)2 is released and preempts \( \int \)3.

- 5. At time 6, J2 executes L(Black) to request Black; L(Black) fails because black is in use by J5. J2 is now directly blocked by J5.
- According to rule 3, \( \int\_5 \) inherits the priority 2 of \( \int\_2 \).
- Because J5's priority is now the highest among all ready jobs, J5 starts to execute
- 6. It is released at time 7. Having the highest priority 1, it preempts Is and starts to execute.

- 7. At time 8, /1 executes *L(Shaded)*, which fails, and becomes blocked. Since /4 has *Shaded* at the time, it directly blocks /1 and, consequently, inherits /1's priority 1.
- J4 now has the highest priority among the ready jobs J3, J4, and J5. Therefore, it starts to execute.
- 8. At time 9, J4 requests the resource Black and becomes directly blocked by J5.
- At this time the current priority of J4 is 1, the priority it has inherited from J1 since

- Therefore, J5 inherits priority 1 and begins to execute.
- 9. At time 11, J5 releases the resource Black. Its priority returns to 5, which was its priority when it acquired Black.
- The job with the highest priority among all unblocked jobs is J4.
- Consequently, J4 enters its inner critical section and proceeds to complete this and the outer critical section.

- ▶ 10. At time 13, J4 releases Shaded. The job no longer holds any resource; its priority returns to 4, its assigned priority.
- ▶ ∫1 becomes unblocked, acquires Shaded, and begins to execute.
- 11. At time 15, /I completes. /2 is granted the resource *Black* and is now the job with the highest priority. Consequently, it begins to execute.
- 12. At time 17, J2 completes. Afterwards, jobs J3, J4, and J5 execute in turn to completion

- From this example, we notice that a high-priority task can experience two kinds of blocking:
- Direct blocking. It occurs when a higher-priority task tries to acquire a resource already held by a lower-priority task. Direct blocking is necessary to ensure the consistency of the shared resources.
- Push-through blocking. It occurs when a medium-priority task is blocked by a low-priority task that has inherited a higher priority from a task it directly blocks. Push-through blocking is necessary to avoid unbounded priority inversion.

- Note that in most situations when a task exits a critical section, it resumes the priority it had when it entered. This, however, is not always true.
- Consider the example illustrated in Figure 7.9. Here, task  $\tau$ 1 uses a resource Ra guarded by a semaphore Sa, task  $\tau$ 2 uses a resource Rb guarded by a semaphore Sb, and task  $\tau$ 3 uses both resources in a nested fashion (Sa is locked first).
- At time t1,  $\tau2$  preempts  $\tau3$  within its nested critical section; hence, at time t2, when  $\tau2$  attempts to lock Sb,  $\tau3$  inherits its priority, P2.

- Similarly, at time t3,  $\tau1$  preempts  $\tau3$  within the same critical section, and at time t4, when  $\tau1$  attempts to lock Sa,  $\tau3$  inherits the priority P1.
- At time t5, when t73 unlocks semaphore t75, task t72 is awakened but t71 is still blocked; hence, t73 continues its execution at the priority of t71.
- At time t6, t3 unlocks Sa and, since no other tasks are blocked, t3 resumes its original priority P3

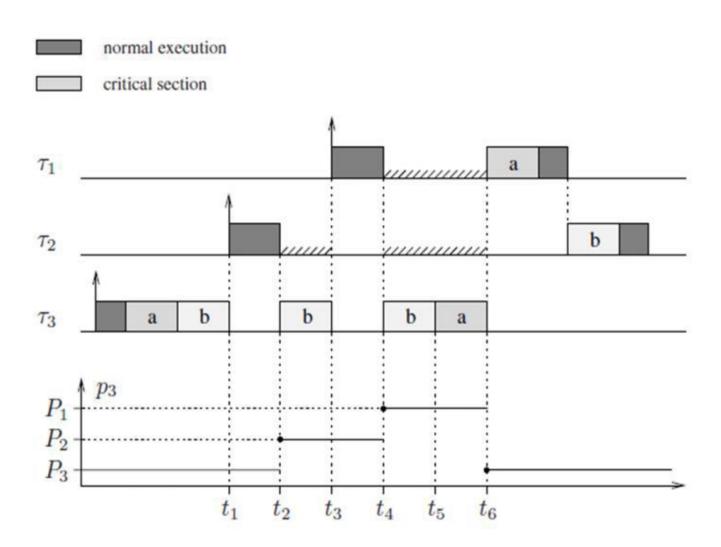


Figure 7.9 Priority inheritance with nested critical sections.

- An example of transitive priority inheritance is shown in Figure 7.10.
- Here, task  $\tau$  1 uses a resource Ra guarded by a semaphore Sa, task  $\tau$ 3 uses a resource Rb guarded by a semaphore Sb, and task  $\tau$ 2 uses both resources in a nested fashion (Sa protects the external critical section and Sb the internal one).
- At time t1, \(\tau^3\) is preempted within its critical section by \(\tau^2\), which in turn enters its first critical section (the one guarded by \(Sa\), and at time \(t^2\) it is blocked on semaphore \(Sb\). As a consequence, \(\tau^3\) resumes and inherits the priority \(P^2\).

- At time t3, τ3 is preempted by τ1, which at time t4 tries to acquire Ra. Since Sa is locked by τ2, τ2 inherits P1. However, τ2 is blocked by τ3; hence, for transitivity, τ3 inherits the priority P1 via τ2.
- When  $\tau$ 3 exits its critical section, no other tasks are blocked by it; thus it resumes its nominal priority P3. Priority P1 is now inherited by  $\tau$ 2, which still blocks  $\tau$ 1 until time  $\tau$ 6.

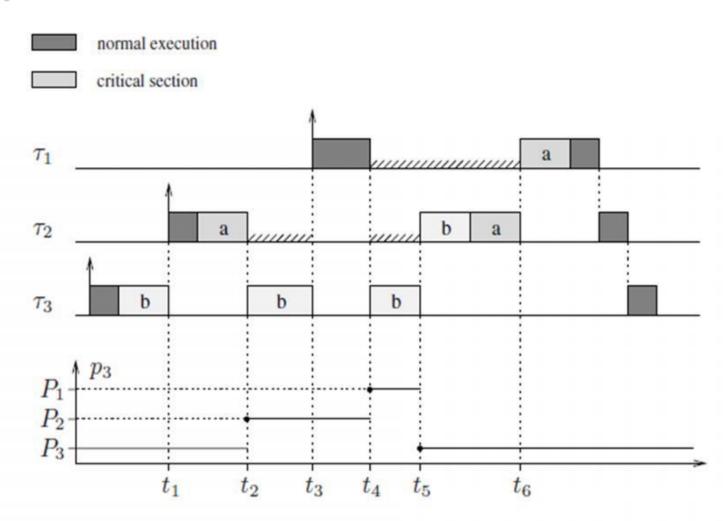


Figure 7.10 Example of transitive priority inheritance.