

$$y_2(x) = x \int \frac{\exp\left[-\int \frac{-2x}{1-x^2} dx\right]}{x^2} dx$$

$$= x \int \frac{\exp[-\ln|1-x^2|]}{x^2} dx = x \int \frac{e^{-\ln|1-x^2|}}{x^2} dx$$

$$= x \int \frac{1}{x^2(1-x^2)} dx = x \int \frac{dx}{x^2(1-x^2)}$$

$$= x \int \left[\frac{1}{x^2} + \frac{1}{2(x+1)} - \frac{1}{2(x-1)} \right] dx$$

$$= x \left[-\frac{1}{x} + \frac{1}{2} \ln|x+1| - \frac{1}{2} \ln|x-1| \right]$$

$$y_2(x) = -1 + \frac{x}{2} \ln|x+1| - \frac{x}{2} \ln|x-1|$$

to prove $y_1(x), y_2(x)$ linearly indep.

نماذج القدرية الجزئية

$$\frac{1}{x^2(1-x^2)} = \frac{1}{-x^2(x^2-1)}$$

$$= \frac{1}{-x^2(x+1)(x-1)} = \frac{A}{x} + \frac{B}{x^2} + \frac{C}{x+1} + \frac{D}{x-1}$$

بمعدل المسألة نجد

$$A=0, B=1, C=\frac{1}{2}, D=-\frac{1}{2}$$

$$\therefore \frac{1}{x^2(1-x^2)} = \frac{1}{x^2} + \frac{y_2}{x+1} + \frac{(-1/2)}{x-1}$$

$$W(y_1, y_2) = \begin{vmatrix} x & -1 + \frac{x}{2} \ln|x+1| - \frac{x}{2} \ln|x-1| \\ 1 & \frac{x}{2x+2} + \frac{1}{2} \ln|x+1| - \frac{x}{2x-2} - \frac{\ln|x-1|}{2} \end{vmatrix} = \frac{-1}{x^2-1} \neq 0$$

Since $-1 < x < 1$

Exercises

1. Prove that the following functions are linearly independent on $\mathbb{I}$

a. $1, e^x, 2e^{2x}$, $\mathbb{I} = (-\infty, \infty)$

b. $x \ln x, \ln x$ $I = (0, \infty)$

c. $1, \sin^2 x, 1 - \cos x$ $I = (-\infty, \infty)$

d. $x, \sqrt{1-x^2}$ $I = (-1, 1)$

② Find wronskian of the solution for the following D.Es.

a. $x^2 y'' + xy' + (x^2 + 1)y = 0$

with $y_2(1) = 1, y_2'(1) = 1, y_1'(1) = 0, y_1(1) = 0$

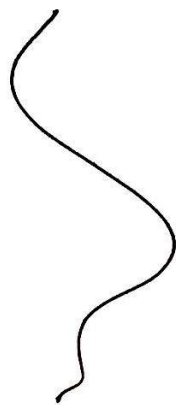
b. $x^2 y'' - 3xy' + y = 0$

with $y_1(0) = 1, y_1'(0) = 0, y_2'(0) = 1, y_2(0) = 0$

③ Find the second solution for the following D.Es. and prove that these solutions are linearly independent

a. $3xy'' - y' = 0, y_1(x) = 1$

b. $y'' + (\tan x)y' - 6(\cot^2 x)y = 0, y_1(x) = \sin^3 x$



Linear Differential Equations of n -th order with constant coefficients

(29)

These D.Es has the form

$$a_0 \frac{d^2 y}{dx^2} + a_1 \frac{dy}{dx} + \dots + a_n y = f(x) \dots \textcircled{1}$$

where $a_0, a_1, a_2, \dots, a_n$ constants

we can solve D.E. $\textcircled{1}$ by many methods

1. Method of operator. ^{المؤثر}
2. Method of undetermined coefficients. ^{طريقة غير المحددة}
3. Method of variation of parameters. ^{تغير التوابيع}

Method of variation of parameters.

It is general method to find particular solution of non-homogenous D.E. In this method we change the arbitrary constants C_i in general solution $\sum_{i=1}^n C_i y_i$ of homogeneous D.E. $Ly=0$ by functions v_i such that $\sum_{i=1}^n v_i y_i$ become particular solution of non-homogenous D.E.

$Ly = h(x)$, hence we called this method the method of ^{طريقة تغير التوابيع (البابوتاري)} variation of parameters.

Theorem (9): If g_1, g_2 are linearly independent solutions of D.E. $L_2 y = 0$, on I . then we can evaluate particular solution y_p of D.E. $L_2 y = h(x)$ from the relation: (30)

$$y_p(x) = \int_{x_0}^x \frac{[g_1(t)g_2(x) - g_1(x)g_2(t)]}{a_0 W(g_1, g_2)(t)} \cdot h(t) dt \quad \text{--- (1)}$$

where $x_0 \in I$.

(تأخذ المشتقتين مؤلفة في الفترة I)

Proof: Let v_1, v_2 be functions in $C^1(I)$ such that $\forall x \in I$

$$y_p(x) = v_1(x)g_1(x) + v_2(x)g_2(x) \quad \text{--- (2) and } \forall x \in I$$

$$v_1'(x)g_1(x) + v_2'(x)g_2(x) = 0 \quad \text{--- (3)}$$

Since $y_p(x)$ is particular solution of the D.E. $L_2 y = h(x)$

$$\text{then } a_0 y_p''(x) + a_1 y_p'(x) + a_2 y_p(x) = h(x) \quad \text{--- (4)}$$

$$\text{from (2) } y_p'(x) = v_1'g_1 + v_1g_1' + v_2'g_2 + v_2g_2'$$

$$\text{from (3) } y_p'(x) = v_1(x)g_1'(x) + v_2(x)g_2'(x)$$

$$y_p''(x) = v_1(x)g_1''(x) + v_1'(x)g_1'(x) + v_2(x)g_2''(x) + v_2'(x)g_2'(x)$$

substituting y_p, y_p', y_p'' in (4) we get:

$$a_0 [v_1g_1'' + v_1'g_1' + v_2g_2'' + v_2'g_2'] + a_1 [v_1g_1' + v_2g_2'] + a_2 [v_1g_1 + v_2g_2] = h(x)$$

$$\Rightarrow a_0 [v_1' g_1' + v_2' g_2'] = h(x) \quad \dots (5)$$

from (3) and (5) we get

$$v_1' g_1 + v_2' g_2 = 0 \quad \dots (3)$$

$$a_0 v_1' g_1' + a_0 v_2' g_2' = h(x) \quad \dots (5)$$

by using Cramer's rule we get :

$$v_1' = \frac{\begin{vmatrix} 0 & g_2 \\ h & a_0 g_2' \end{vmatrix}}{\begin{vmatrix} g_1 & g_2 \\ a_0 g_1' & a_0 g_2' \end{vmatrix}} = \frac{-h g_2}{a_0 g_1 g_2' - a_0 g_1' g_2} = \frac{-h g_2}{a_0 [g_1 g_2' - g_1' g_2]}$$

$$\Rightarrow v_1' = \frac{-h g_2}{a_0 w(g_1, g_2)(x)}$$

also

$$v_2' = \frac{\begin{vmatrix} g_1 & 0 \\ a_0 g_1' & h \end{vmatrix}}{\begin{vmatrix} g_1 & g_2 \\ a_0 g_1' & a_0 g_2' \end{vmatrix}} = \frac{h g_1}{a_0 g_1 g_2' - a_0 g_1' g_2} = \frac{h g_1}{a_0 w(g_1, g_2)(x)}$$

نلاحظ

$$v_1 = - \int_{x_0}^x \frac{g_2(t) h(t)}{a_0 w(g_1, g_2)(t)} dt \quad v_2 = \int_{x_0}^x \frac{g_1(t) h(t)}{a_0 w(g_1, g_2)(t)} dt$$

Substituting in (2), we get the required relation