

Lecture 6

–Priority Scheduling Algorithm

Priority scheduling is one of the most common scheduling algorithms to schedule tasks based on their priority. Each task is assigned a priority value based on specific criteria.

The task with the highest priority is selected for execution first. If there are multiple tasks sharing the same priority, they are scheduled in the order they arrived, following a First-Come, First-Served approach.

Priority Scheduling can be implemented in two ways:

- Non-Preemptive Priority Scheduling
- Preemptive Priority Scheduling

Non-Preemptive Priority Scheduling Algorithm

In Non-Preemptive Priority Scheduling, the machine is not taken away from the running task. Even if a higher-priority task arrives, the currently running task will complete first; that means a high-priority task must wait until the currently running task finishes.

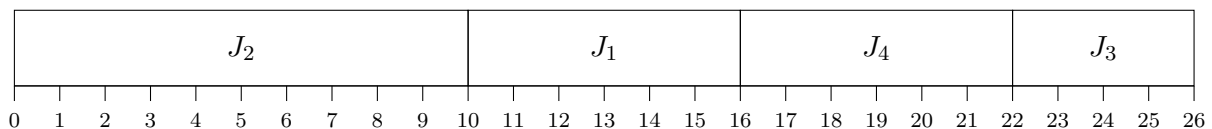
Examples of Non-Preemptive Priority Scheduling

Example 1:

Suppose that we have a set of four jobs that have arrived at the same time in the order J_1 , J_2 , J_3 and J_4 . The processing time in milliseconds and the priorities of the tasks is given by the following table

J_i	p_i	Priority
J_1	6	2
J_2	10	1
J_3	4	3
J_4	6	2

Considering that a lower priority value means higher priority, let us perform non-preemptive priority scheduling on it. We will draw the Gantt chart and find the average of the waiting time, completion time and Flowtime.



J_i	C_i	W_i	F_i
J_1	16	10	16
J_2	10	0	10
J_3	26	22	26
J_4	22	16	22
Average	18.5	12	18.5

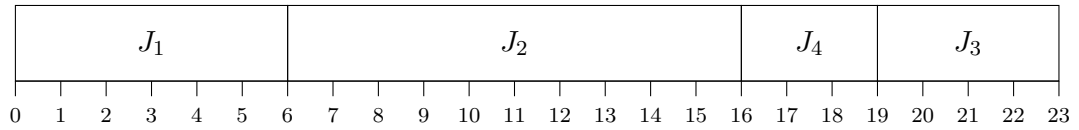
Example 2:

In this example, we consider a situation when the tasks arrive at different times. Suppose we have set of four tasks whose arrival times, processing times and priorities are as follows

J_i	r_i	p_i	Priority
J_1	0	6	2
J_2	4	10	1
J_3	4	4	2
J_4	8	3	1

Let us draw the Gantt chart and find the average of the waiting time, completion time and Flowtime using non-preemptive priority scheduling, considering lower priority value as higher priority.

At time 0ms, only J_1 is there, and so it is assigned to the machine. J_1 completes execution at 6ms, and at that time, J_2 and J_3 have arrived. J_2 has higher priority and hence is assigned to the machine. J_2 completes execution at time 10ms. By that time, J_4 has arrived, having priority value 1, and so it is assigned to the machine. Once J_4 completes execution, J_3 is assigned to the machine. So the order of execution is J_1, J_2, J_4, J_3 as shown in the following Gantt chart.



J_i	C_i	W_i	F_i
J_1	6	0	6
J_2	16	2	12
J_3	23	15	19
J_4	19	8	11
Average	16	6.25	12

Preemptive Priority Scheduling

In Preemptive Priority Scheduling, the machine can be taken away from the currently running task if a new task with a higher priority arrives. For example, a low-priority task is running, and a high-priority task arrives; the machine immediately switches to the high-priority task.

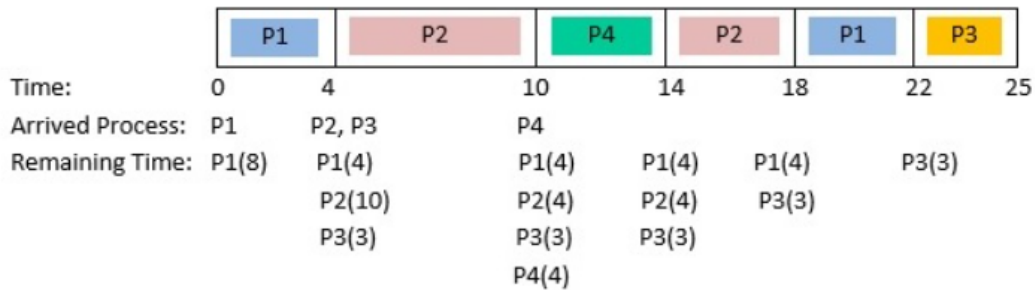
Example of Preemptive Priority Scheduling

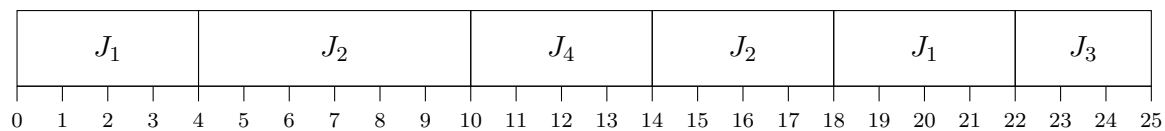
Let us consider the following set of jobs whose arrival times, processing times and priorities are give in the following table

J_i	r_i	p_i	Priority
J_1	0	8	3
J_2	4	10	2
J_3	4	3	3
J_4	10	4	1

Gantt Chart

At time 0ms, J_1 is the only job and so it starts executing. At time 4ms, J_2 and J_3 arrive. Since J_2 has higher priority than J_1 , J_2 preempts J_1 . At 10ms, J_4 arrives, which has higher priority than J_2 and so pre-empts J_2 . J_4 completes execution at 14ms and leaves. The jobs in the system are J_1 , J_2 , and J_3 , among which J_2 has the highest priority and so is assigned to the machine. At 18ms, J_2 completes execution, and so J_1 and J_3 are the jobs in the system. Since both jobs are of the same priority, the scheduler selects J_1 by the FCFS method. When J_1 completes execution, finally J_3 executes. The following Gantt chart shows the order of execution





J_i	C_i	W_i	F_i
J_1	22	14	22
J_2	18	4	14
J_3	25	18	21
J_4	14	0	4
Average	19.75	9	15.25